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E60/E61 xDrive with DSC8+

Model: 525xi, 530xi, 530xiT

Production: From April 2005

OBJECTIVES

After completion of this module you will be able to:

- Familiarize yourself with DSC8+ features
- Explain the xDrive mechanical operation
- Describe the xDrive power flow

xDrive with DSC8+

From 04/2005, the BMW 5 Series wagon and sedan (optional) will have all wheel drive capability utilizing the tried and tested all-wheel drive system xDrive of the X3 and X5.

The innovative all-wheel xDrive is a system for controlling and regulating the “infinitely” variable drive torque distribution over the front and rear axle. The xDrive uses the system functions of the DSC to positively influence the vehicle handling by specifically distributing the power in the event of understeer or oversteer.

With the controlled multi-disc clutch in connection with the xDrive it is now possible to resolve the conflict between traction and vehicle handling.

This is been achieved in that the xDrive does not predefine the torque distribution by a fixed transmission ratio as is the case with the previous systems. Instead, distribution of the drive torque is dependent on the clutch lockup torque of the controlled multi-disc clutch in the transfer case and on the transmitted torque at the front and rear axle.

Driver Benefits

In addition to the previous functions, a series of additional safety and comfort functions will now be available to the driver with the introduction of the DSC8+ in the E60/E61.

The expanded DSC8+ functions include:

- Dry braking
- Brake standby
- Automatic soft-stop
- Fading warning and assistance
- Drive-off assistant
- Hill descent control HDC

Besides the outstanding chassis characteristics of the BMW 5 Series, the all wheel drive system offers traction advantages not only on snow and ice but also on unsurfaced roads.

Note: Because many system components and functions and are shared between the xDrive and DSC8+ system, they will be discussed together in this section.

xDrive

The innovative xDrive four-wheel drive is a system that controls and regulates the distribution of driving torque to the front and rear axles. The measured variables of DSC are used by xDrive but are also influenced by modified handling performance.

The multi-disc clutch is the heart of the xDrive. By using the controlled multi-disc clutch, it is possible to resolve the conflict between traction and handling performance.

This is achieved through the fact that torque distribution is not determined by a fixed gear ratio in the xDrive as was the case in the previous systems. Instead, the distribution of driving torque is dependent on the locking torque of the controlled multi-disc clutch in the transfer case and on the transferable torque to the front and rear axles.

DSC8+

The DSC8+ system adds features to the DSC8 system already in use in the E60 sedan and combines features used in other DSC systems (E53/83). Due to the mechanical composition of the xDrive system, the programming for DSC regulation has also been changed.

Present DSC8 functions:

- ABS Anti-lock Braking System
- ADB Automatic Differential Brake
- EBV Electronic Braking Force Distribution
- CBC Cornering Brake Control
- ASC Automatic Stability Control
- DSC Dynamic Stability Control
- DBC Dynamic Brake Control
- MSR Engine Drag Torque Control

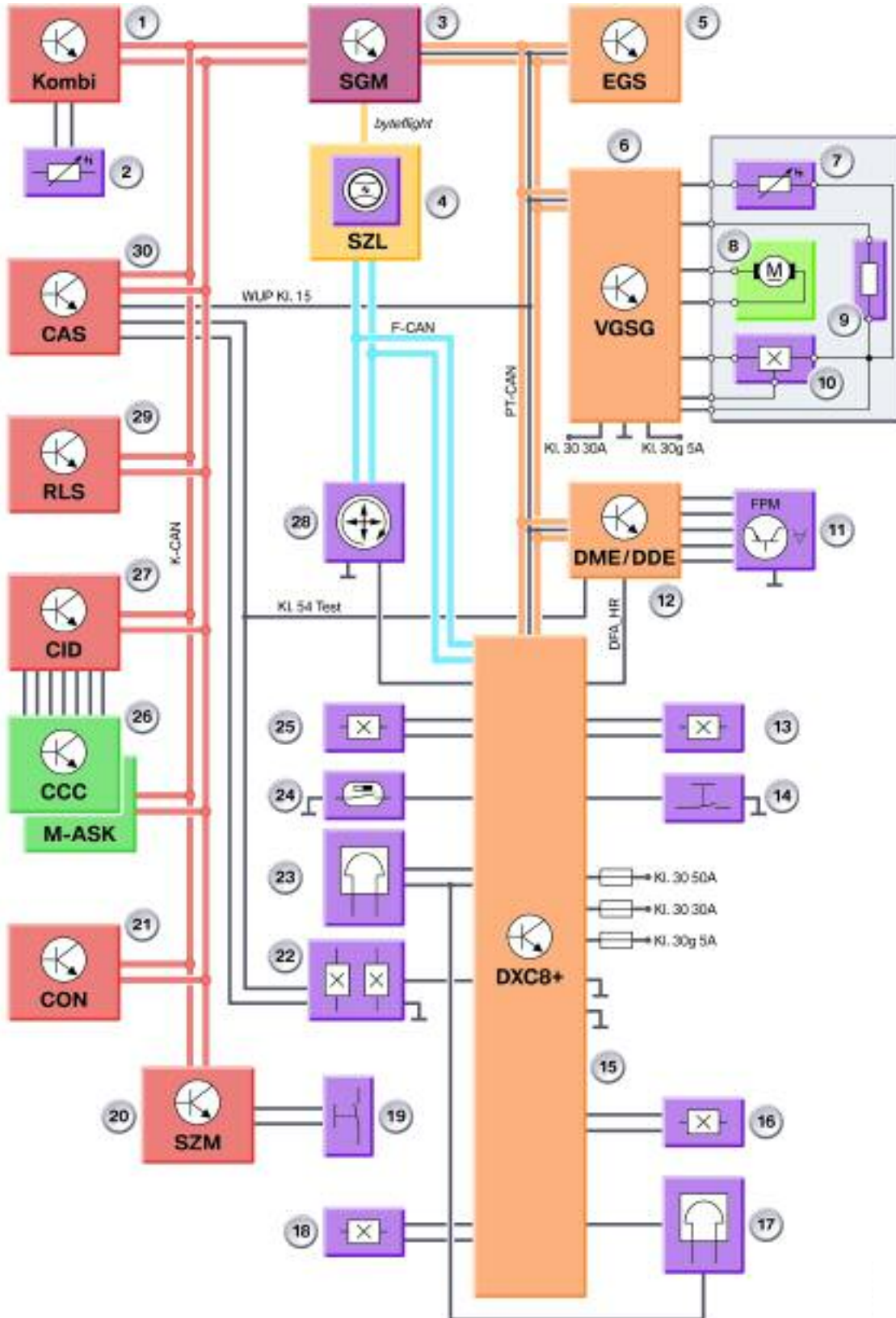
Present DSC functions:

- TCC Transfer Case Control
(control of multi-disc clutch in transfer case)
- ASC-X Automatic Stability Control X
(special function for all-wheel drive vehicles)
- ADB-X Automatic Differential Brake X
(special function for all-wheel drive vehicles)
- HDC Hill Decent Control

New DSC/DSC8+ functions

- Dry braking
- Automatic soft stop
- Drive-off assistant
- Hill descent control HDC
- Brake standby
- Fading assistance
- Trailer stabilization control

System Circuit Diagram



System Circuit Diagram Legend

Index	Explanation
1	Instrument cluster
2	Outside temperature sensor
3	Safety and gateway module (SGM)
4	Steering column switch cluster (SZL) with HDC button
5	Electronic transmission control module (EGS)
6	Transfer case control unit (VGSG)
7	Temperature sensor
8	Electronic motor, actuator drive
9	Coding resistor
10	Motor position sensor
11	Accelerator pedal module (FPM) - (not for US)
12	Digital motor electronics (DME) control unit
13	Wheel speed sensor, front right
14	Handbrake switch
15	Dynamic traction control (DSC8+)
16	Wheel speed sensor, rear right
17	Brake wear sensor, rear right
18	Wheel speed sensor, rear left
19	DSC button
20	Center console switching center (SZM)
21	Controller (CON)
22	Brake light switch (BLS)
23	Brake wear sensor, front left
24	Brake fluid level sensor
25	Wheel speed sensor, front left
26	CCC or M-ASK
27	Central information display
28	Yaw rate/longitudinal/transverse acceleration sensor (Y-sensor-2)
29	Rain light sensor (RLS)
30	Car Access System (CAS)

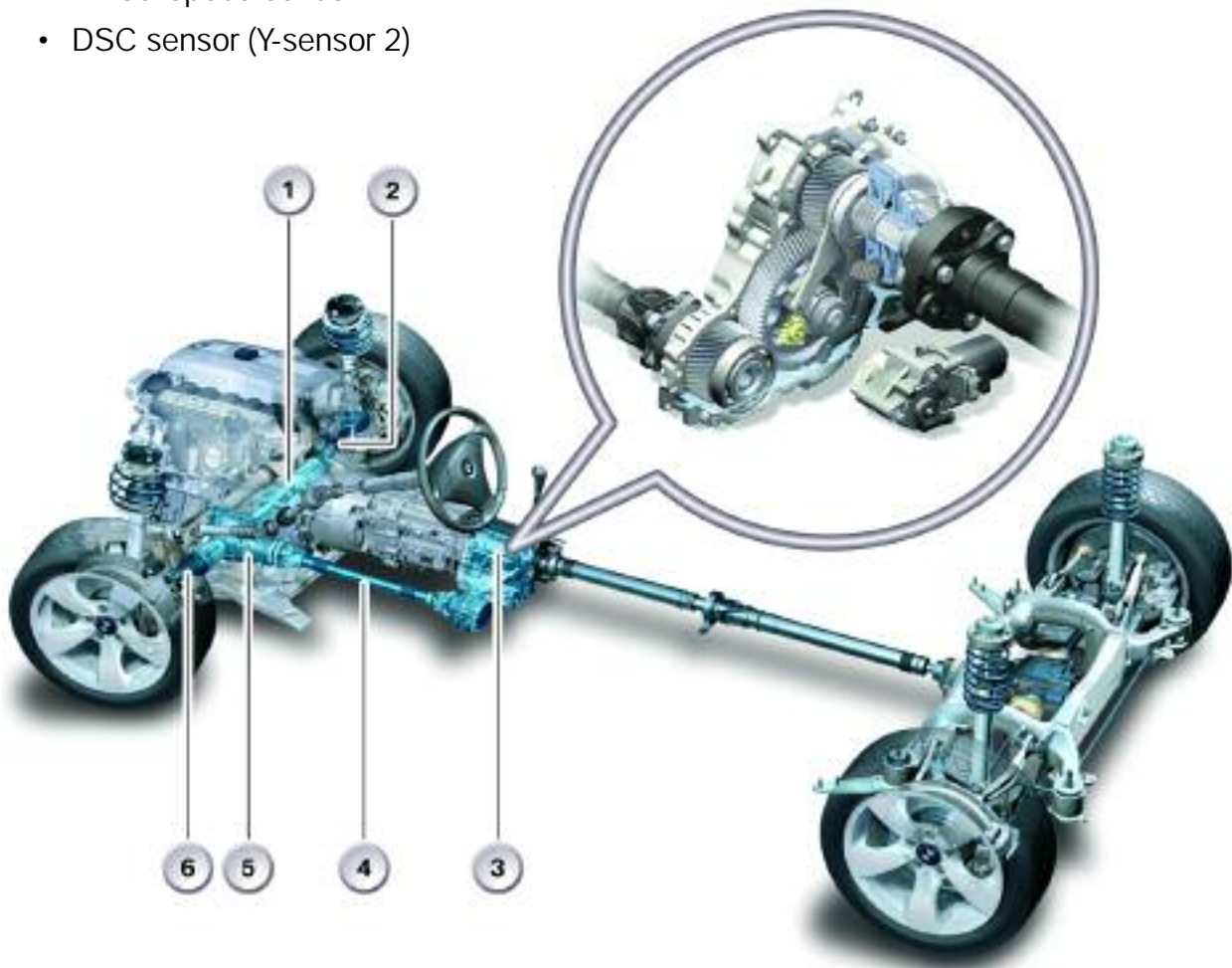
NOTES

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System Components

The xDrive/DSC8+ system is composed of the following major components:

- ATC 300 transfer case
- Adjusting levers
- Servomotor with motor position and temperature sensor
- Coding/classification resistor
- Transfer case control unit
- DSC8+ control unit
- Wheel speed sensor
- DSC sensor (Y-sensor 2)



Index	Explanation	Index	Explanation
1	Oil Pan lead through	4	Propeller shaft to front axle
2	Right drive shaft, front	5	Front axle differential
3	Transfer case	6	Left drive shaft, front

ATC 300 Transfer Case

The transfer case ATC 300 (Active Torque Control) is used on the E60/E61.

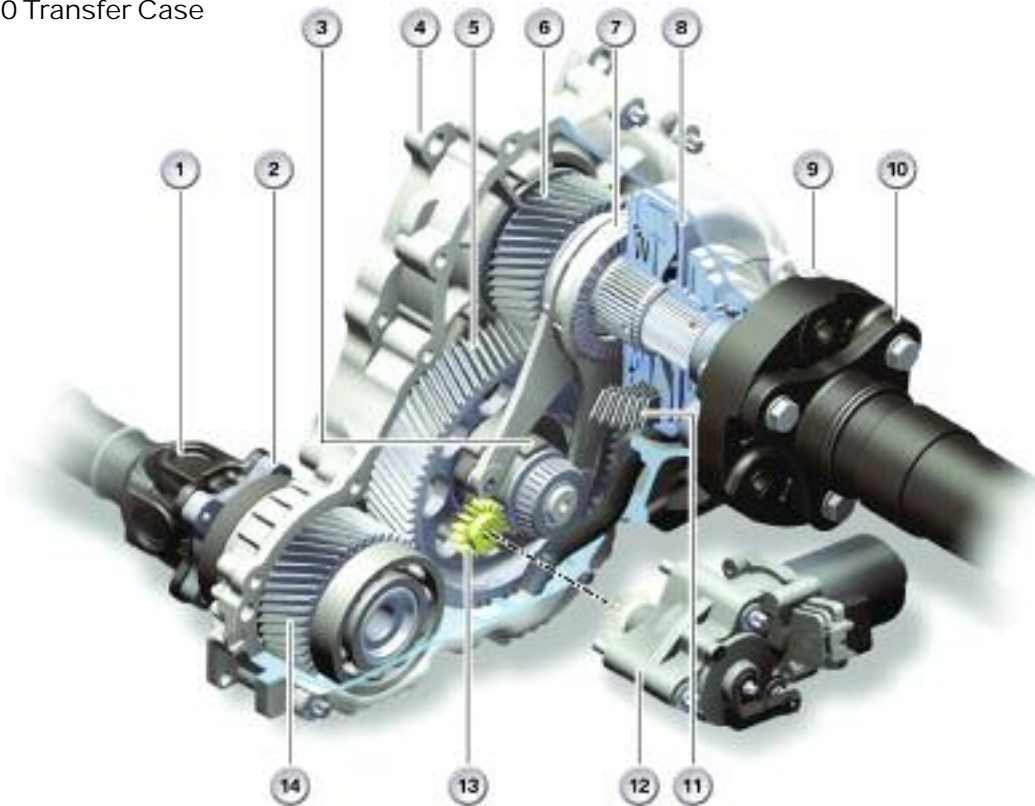
In view of the restricted package space of the transmission tunnel in the BMW 5 Series, it was not possible to adopt the transfer case from the BMW X3 (ACT400) with the same torque rating.

On the BMW 5 Series it was not possible to drive the forward power flow diagonally as is the case on the X3 with a chain, but rather it is necessary to divert it L-shaped with the aid of spur gears (pinions), resulting in a modified design of the transfer case.

The actuator drive and the actuation of the control lever were also modified. The clutch package remains unchanged. The forward connection is provided by a bolted on drive shaft.

The flange of the ATC transfer case is the same for automatic and manual transmissions.

ATC 300 Transfer Case



Index	Explanation	Index	Explanation
1	Propeller shaft to front axle	8	Clutch housing
2	Drive flange to front axle	9	Output flange to rear axle
3	Control cam	10	Propeller shaft to rear axle
4	Transfer case	11	Disc package
5	Idler gear	12	Actuator drive
6	Drive gear	13	Drive pinion
7	Control lever	14	Output gear

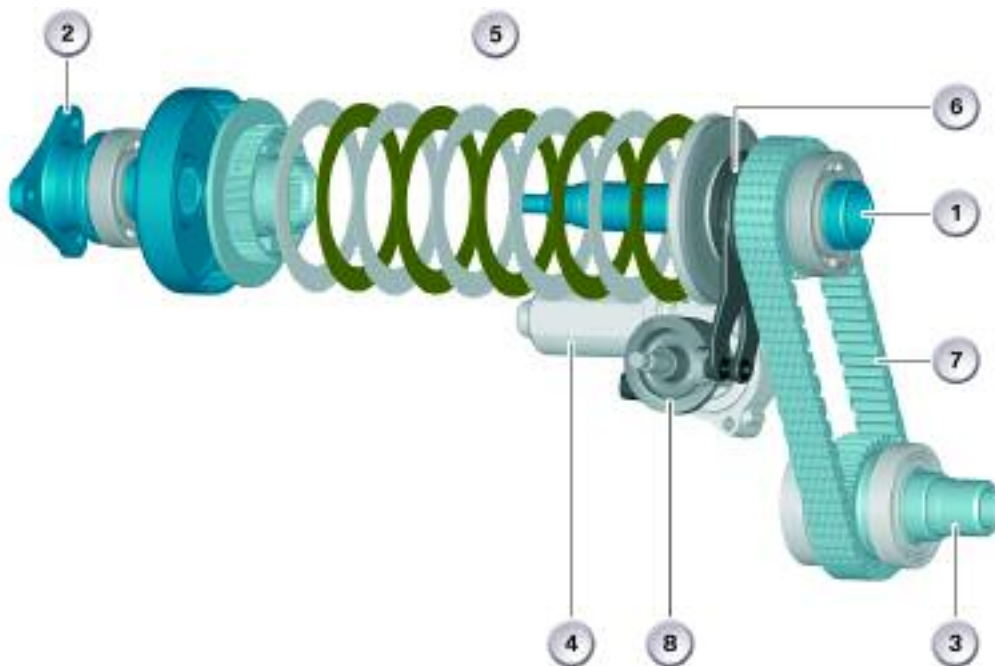
The ATC 300 is installed in the E61 and E60 all wheel drive models. The ATC 400 is installed in the E83 and the ATC 500 in the E53 MU.

The ATC 300 differs from the other transfer cases because it is gear driven not chain driven. The basic functions and operations remain unchanged.

The difference between the transfer cases are:

- ATC 400 & 500 are chain driven vs. ATC 300 which is gear driven
- ATC 300 & 400 uses a four bolt flange to connect to the front propeller shaft vs. ATC 500 which uses a splined connection
- ATC 500 utilizes one more disc in the multi-disc clutch than the ATC 300 & 400
- ATC 500 has 19mm greater length between the input shaft and the output shaft to the front axle than the ATC 400. (the ATC 300 uses gears not a chain)

ATC 500 Transfer Case



Index	Explanation	Index	Explanation
1	Input from manual / automatic transmission	5	Clutch discs
2	Output to rear axle prop. shaft	6	Adjusting levers with ball ramp
3	Output to front axle prop. shaft	7	Chain
4	Servomotor	8	Disc cam

Adjusting Levers

The actuator drive unit operates such that the drive pinion rotates and engages via the gearing in the control cam. In turn, the control cam is rotated and the control lever pressed apart.

The rotary motion is converted into an axial force by the ball ramps in the control lever. The axial force that compresses the disc package in the multi-disc clutch is proportional to the transmitted torque of the multi-disc clutch.

The position of the control lever is infinitely variable and allows exact regulation of the control cam by the actuator drive unit.



Servomotor with Motor Position Sensor

The actuator drive unit is a DC motor with worm drive. It also features a Hall sensor that serves the purpose of determining the position and the adjustment speed of the motor shaft. The position of the motor shaft determines the closing rate of the multi-disc clutch.

There is also a temperature sensor installed in the motor that signals the temperature to the transfer case control unit (VGSG). A temperature model is calculated in the VGSG for the purpose of protecting the motor from overload. For this purpose, the maximum closing rate is reduced in various stages.

If these measures are not sufficient to protect the motor from overload, the control is interrupted and the clutch completely opened so that only rear axle drive is now possible.



Index	Explanation
1	Magnetic ring
2	Motor position sensor (Hall sensor)

Coding Resistor

Because of mechanical tolerances in production, the characteristic curve of the multi-disc clutch locking torque varies slightly.

Once the actual locking torque has been measured on the clutch test bench, a resistor is attached to the servomotor; the resistor's value is a reference to the locking torque characteristic.

Each time the engine is started, the transfer case control unit measures the resistance value once and the optimum program map for the transfer case fitted is selected.



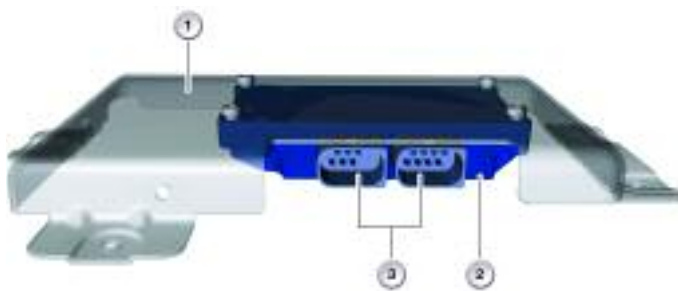
Index	Explanation
1	Drive pinion
2	Electric motor
3	Coding resistor
4	Actuator drive housing

Transfer Case Electronic Control Unit

The transfer case control unit (VGSG) is on CAN-bus.

Depending on the vehicle, the module is installed in the following location:

- E60/61 - under the rug forward of the passenger's front seat
- E83 (X3) - under the rear floor panel of the cargo compartment trim
- E53 (X5) - under the rear bench on the left side



Index	Explanation
1	Kick guard
2	Transfer case control unit
3	Connector

DSC8+ Control Unit

The DSC8+ control unit is installed in the engine compartment essentially consists of three components:

- Add-on control unit
- Valve block with integrated pressure sensors
- Pump motor

The newly developed changeover valves permit even more exact control in the low pressure range, resulting in the following advantages:

- Reduction of control noise
- Improvement in control quality and control comfort
- Improvement in automatic brake intervention by the active/dynamic cruise control ACC/DCC
- Improvement in the control accuracy of the HDC function
- Realization of additional brake functions

Wheel Speed Sensor

Active wheel speed sensors with an integrated evaluator circuit are used together with the xDrive.

The active wheel speed sensors require a power supply for their operation. The output signal is sent as a data protocol based on the pulse-width modulation method (PWM). The PWM signal is used for the purpose of determining the road speed. The pulse width contains additional information relating to the direction of rotation, standstill detection, installation position detection, and air gap reserve to the sensor ring. (example : sends one pulse every 0.75 s when the wheel is stationary)

The direction of rotation is determined by the internal signal offset of three correspondingly arranged Hall-effect elements in the sensor.

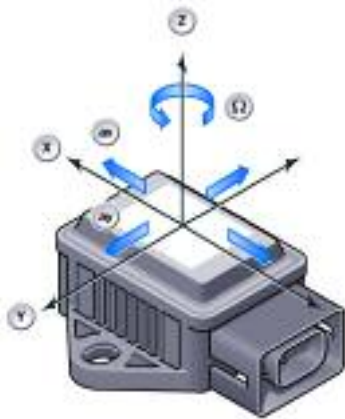


Index	Explanation
1	Sensor ring
2	Sensor-IC with Hall sensor
3	Sensor housing

DSC Sensor

The DSC sensor (Y-sensor 2) is installed under the front passenger's seat next to the transmission tunnel.

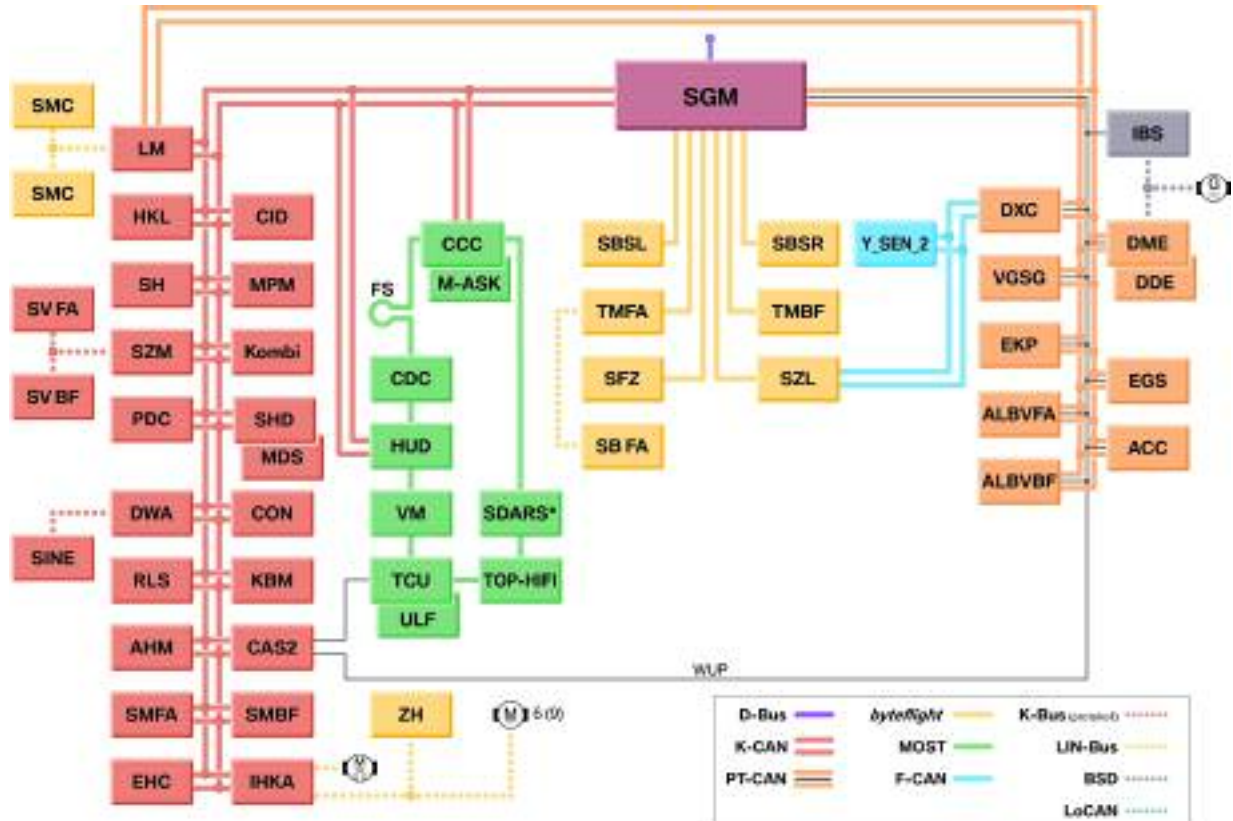
In addition to the previous yaw rate and transverse acceleration sensor, the DSC sensor also contains an additional longitudinal acceleration sensor for the drive-off assistant function.



Index	Explanation
X	Longitudinal axis
Y	Transversal axis
Z	Vertical axis
ax	Longitudinal acceleration
ay	Lateral acceleration
Ω	Yaw rate

Bus Overview

The transfer case control unit (VGSG) is on the PT-CAN. VGSG shares information with DSC for overall xDrive control and has diagnostic communication.



Bus Topology Chart of E61 Sports Wagon (530xiT)

Principles of Operation

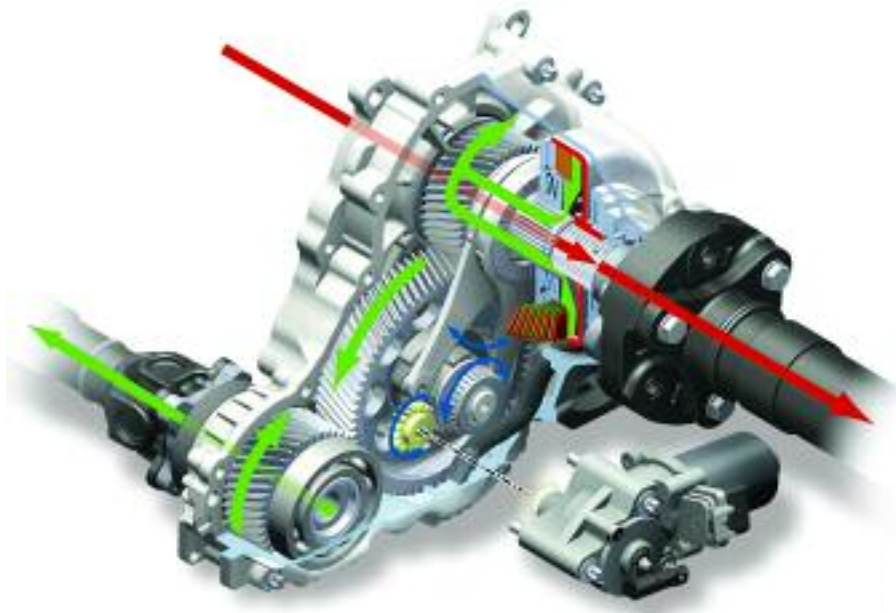
Power Flow

When the multi-disc clutch in the transfer case is disengaged, no driving torque is transmitted to the front axle. All of the driving torque is then distributed to the rear axle. This is because the input shaft (1) is splined providing a permanent connection to the rear axle propeller shaft output flange (2). The multi-disc clutch couples the rear axle propeller shaft output flange to the front propeller shaft output (3).

The driving torque on the front axle is increased or decreased by regulating the locking pressure of the multi-disc clutch, providing a stepless coupling of the front axle to the drivetrain. This depends on driving situations and road conditions. When the multi-disc clutch is fully engaged, the front and rear axles turn at the same speed.

Driving torque distribution (front/rear) is based on available traction at each axle. For example, when traction is identical on the front and rear axles and a driver accelerates from a stop in first gear at full throttle, the rear axle is capable of sustaining greater driving torque as the vehicle weight shifts from the front to the rear.

Another example is when the front axle is on a high traction surface and the rear axle is on ice. In this case, virtually 100% of the available driving torque is transmitted to the front axle. Based on available traction, virtually no driving torque can be supported by the rear axle. Obviously, when more driving torque is transmitted to the front axle, driving torque on the rear axle is proportionally reduced due to lack of traction.



Color	Explanation
Red	Torque from engine to rear axle
Green	Controlled torque to front axle
Dark Blue	Rotation to drive multi-disc clutch

DSC/DSC8+ Control Unit

As in the earlier DSC control units, there are two microprocessors incorporated in the add on DSC8+ control unit. The difference is that in the DSC8 and DSC8+ both processors do not calculate the same algorithms but rather one processor is responsible for performing control and monitoring calculations and checking the plausibility of the wheel speeds.

There are also two semiconductor relays integrated in the DSC8+ control unit, one for the pumpmotor and the other for the solenoid valves.

On exceeding a road speed of 6 km/h, an electronic self-test is started, during which the pump motor and all solenoid valves are briefly actuated. If the brake is operated at a driving speed of 6 km/h, as may be the case with "two-foot drivers", the self-test will be performed at a speed of 15 km/h.

The check of the wheel speed signals is already started at a speed of 2.75 km/h.

In connection with the xDrive, the DSC8+ control unit also undertakes the task of calculating the lockup torque for the multi-disc clutch in the transfer case.

The lockup torque is always optimally set and controlled to suit the corresponding driving situation.

The drive torque distribution over the front and rear axles is based on the lockup torque. The lockup torque to be set is derived from the pilot control and from a higher-ranking traction and vehicle dynamics regulator corresponding to the driving situation.

The DSC8+ control unit sends the data, concerning the lockup torque, on the PT-CAN to the transfer case control unit VGSG.

Conversely, the transfer case control unit signals the lockup torque actually set as well as the load on the transmission fluid, electric motor and multi-disc clutch.

Transfer Case (VGSG) Control Unit

The transfer case control unit serves the purpose of regulating the lockup torque of the multi-disc clutch in the transfer case and therefore to distribute the drive forces between the front and rear axle corresponding to requirements.

The transfer case control unit receives the necessary torque request from the DSC8+ control unit and adjusts the currently required clutch lockup torque accordingly.

The function required for this task is the transfer case control (TCC). The control and power electronics circuitry required for the actuator drive is integrated in the transfer case control unit.

The requirement to set the necessary clutch lockup torque is converted to a corresponding rotary movement of the actuator motor. After turning off the engine, a reference run is performed in order to be able to assign a corresponding clutch lockup torque to a defined angle setting of the actuator motor, while also taking into account the effects of wear.

During the course of the reference run, the clutch is fully closed and opened once. The power intake is measured at the respective angle setting of the actuator motor during the

opening and closing operation so as to determine the beginning and end of the clutch closing procedure. The angle setting is determined by means of a Hall sensor integrated in the actuator motor.

A clutch and oil wear model is additionally calculated in the transfer case control unit.

Where necessary, this model limits the lockup torque in order to reduce friction.

In the event of DSC failure, an emergency strategy for driving the transfer case clutch is integrated as a fall-back level in the transfer case control unit in order to maintain all-wheel drive also in this case.

Transfer Case Control

Control of the lockup torque of the multi-disc clutch in the transfer case facilitates infinitely variable coupling of the front axle to the drive train.

As a result, the drive torque at the front axle can be increased or reduced corresponding to the driving situation and the condition of the road. When the torque at the front axle is increased, the drive torque at the rear axle is, of course, reduced by this torque.

The advantages of variable distribution of the drive torque at the front and rear axles are:

- Optimum utilization of the lateral cornering and wheel peripheral forces applied at the front and rear axles.
- Brake interventions by the DSC are required considerably later, thus increasing overall comfort.
- Compared to a transfer case with fixed transmission ratio (open longitudinal differential) and DSC, with xDrive the drive torque distribution is considerably improved in connection with greatly differing friction values at the front and rear axles.

Even when DSC is turned off, TCC is still active to ensure maximum traction and vehicle dynamics.

Permanent all-wheel drive is cancelled to a large extent or completely in only three control situations:

- When negotiating extremely tight corners with little engine torque in order to allow speed equalization between the front and rear axle (e.g. parking)
- At speeds in excess of 180 km/h
- In extreme understeer driving situations

The control algorithm of the transfer case clutch control can be described in three main modules:

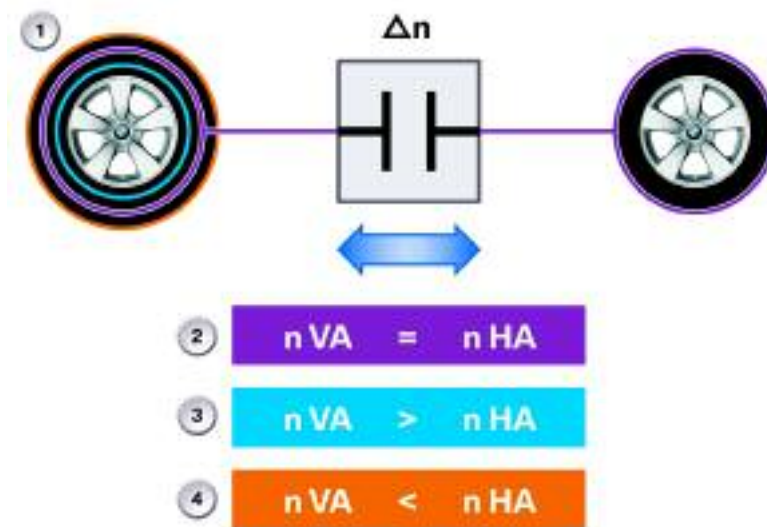
- Tire tolerance logic
- Pilot control
- Traction control/vehicle dynamics control

■ Tire Tolerance Logic

The tire tolerance logic detects different tread circumferences on the front and rear axles. This occurs when:

- Mixed tires are used
- Space saving spare tire is installed
- Tires are used that have been worn down to different levels

Normally, tire circumference deviations result in drivetrain torque bias (unwanted variations).



Index	Explanation	Index	Explanation
nVA	Wheel speed at front axle	2	Identical rolling circumference on both axles
nHA	Wheel speed at rear axle	3	Front axle circumference less than rear axle
1	Different rolling circumferences on front axle	4	Rear axle circumference less than front axle

The tire circumference can fluctuate up to 1% or more as a result of mixed tires or wear. The tire tolerance logic decides depending on the driver's command and driving situation whether the slip is to occur in the transfer case clutch or at the contact area between tire and road.

If the slip is permitted in the transfer case clutch, the locking pressure set by the pre-control is reduced in order to keep the work loss low. In the driving dynamic control situation, the clutch is locked slightly more than normal, the four wheel drive is always guaranteed when required.

For maximum xDrive performance, tires (and wheels) of the same diameter should be installed on the vehicle.

■ Pilot Control

The pilot control algorithm reflects the driver's choice and calculates the necessary lock-up torque as a function of:

- accelerator pedal value,
- engine torque,
- engine speed,
- vehicle speed,
- gear and
- steering angle

while taking into account the maximum load on the clutch, transfer case and axle drive.

The clutch is operated with minimum slip during normal vehicle operation, making available permanent all-wheel drive with a drive torque distribution of 40 % at the front axle and 60 % at the rear axle.

Even in the case of greatly differing frictional values at the front and rear axle, e.g. when the rear axle is on a sheet of ice, the pilot control ensures extremely rapid system response as illustrated in the graphic below.

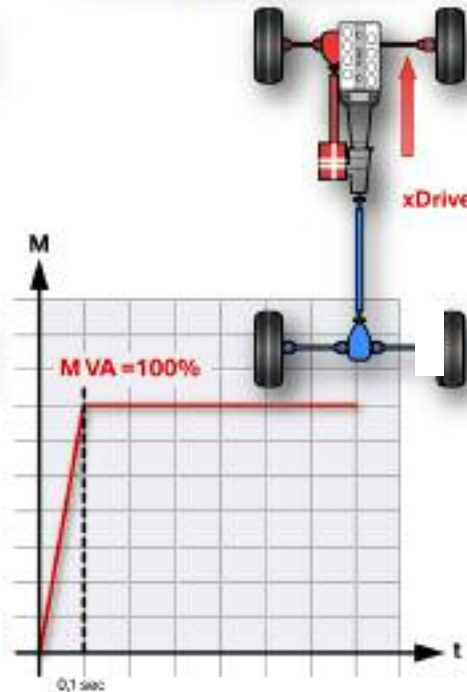
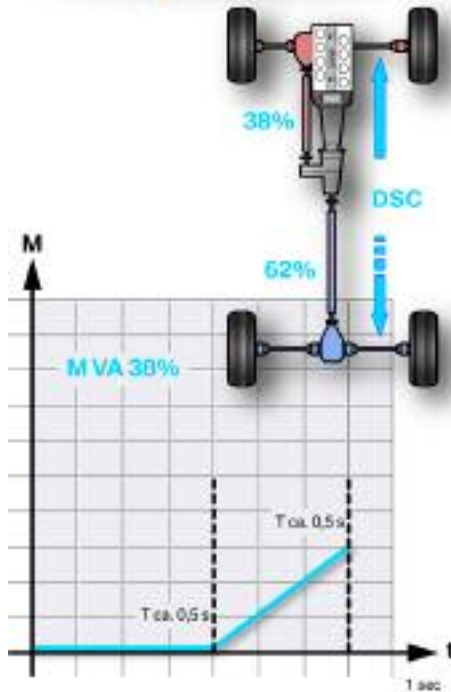
In addition, as opposed to a transfer case with fixed gear ratio (open longitudinal differential), with xDrive no brake intervention is required at the rear axle in this case as no slip can occur.

In the open longitudinal differential system, the brake is applied on detecting slip at the rear axle. Consequently, 62% of the drive torque is applied at the two rear brake discs so that only 38% of the drive force is available at the front axle for the purpose of driving off the sheet of ice. This takes significantly less time (approx. one/tenth of a second).

"Open" Transfer Case

vs.

xDrive



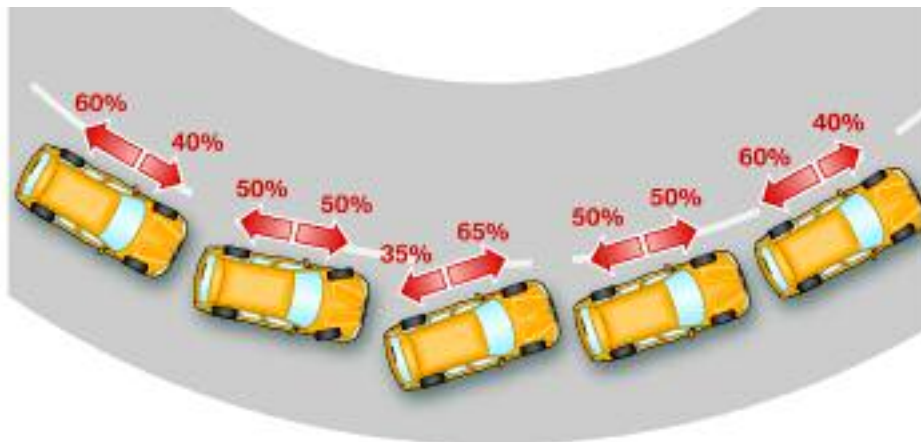
Index	Explanation
M	Driving Torque
M VA	Driving torque on front axle
t	Time

■ Traction Control / Driving Dynamics Control

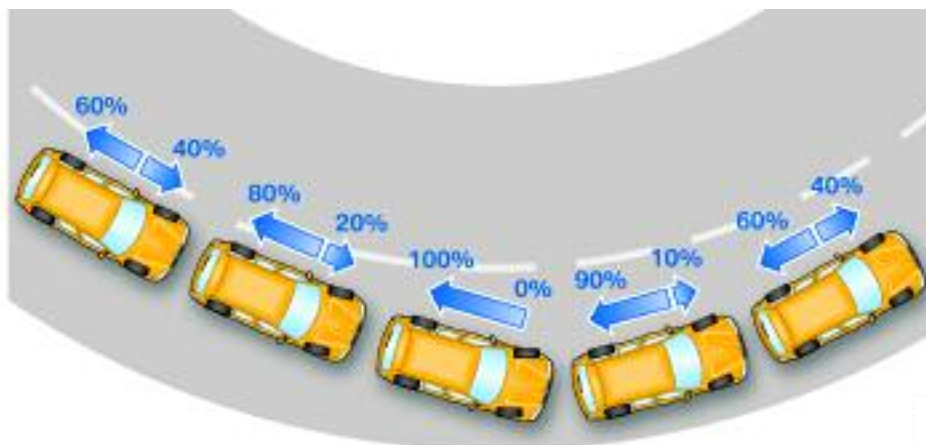
Traction control monitors the slip conditions on the front and rear axles. The wheel speeds, yaw rate and transversal acceleration serve as the input signals.

The function of traction control/driving dynamics control is to achieve optimum traction and to keep the vehicle stable.

As seen in the following graphic, in the event of an oversteer tendency, the transfer case clutch is completely engaged and the maximum supportable driving torque on the front axle is transmitted. This helps to “pull” the front of the vehicle until stability is achieved.



In the event of an understeer tendency, the clutch can be fully disengaged if necessary. In this example, the front axle is separated from the drivetrain and the driving torque can only be transmitted to the rear axle. This helps to “push” the rear of the vehicle until stability is achieved.



■ Limp Home Operation

In order to maintain the four wheel drive function for as long as possible even in the event of important sensor signal failures or failure of the DSC control unit, a limp home control is integrated in the transfer case control unit. This control operates in redundancy to the transfer case clutch control in the DSC control unit. The limp home control contains only two control functions, pre-control and traction-slip control.

The wheel speed signals are very important to traction/slip control. Engine signals, steering angle and yaw are used predominantly for pre-control. If individual sensor signals fail, substitute values are calculated and the relevant functions operated with extended control thresholds.

This strategy is continued until useful four wheel drive control is no longer possible. In this event, the driver is alerted by the DSC/xDrive lamp coming on in the instrument cluster and also by an acoustic warning signal (gong).

Faulted wheel speed signals on the rear axle are calculated by driving or engine speed (remember, the rear wheels are always driven). If the front wheel speed signals fail, the values of the rear axle are adopted. Wheel speeds also substitute for a faulty steering angle signal.

Note: On a vehicle equipped with an automatic transmission, when driving onto brake analyzers, move the selector lever to the "N" position. On a vehicle equipped with a manual transmission, do not press the accelerator pedal once on the brake analyzer. This keeps the transfer case clutch open and the vehicle cannot be pulled off the analyzer.

Dynamic Stability Control

DSC8+ offers several new features from April 2005 production vehicles. They are:

- ASC-X / ADB-X
- Hill descent control HDC
- Dry braking
- Brake standby
- Automatic soft stop
- Fading assistance
- Drive-off assistant
- Trailer stabilization control

■ ASC-X / ADB-X

Unlike regular road vehicles, SAVs are also meant to demonstrate satisfactory handling characteristics and appropriate traction on unconventional roads. In order to provide optimum propulsion with sufficient cornering stability on both normal roads and other road surfaces, Automatic Stability Control X (ASC-X) contains a detection function to distinguish between them.

When off-road terrain is detected, wheel slip threshold is increased to provide sufficient traction force with the increased levels of traction loss.

ASC-X is supplemented by the Automatic Differential Brake (ADB-X) function, which applies the brakes to the wheels per axle, for side to side torque transfer. For example, when a wheel is spinning on one side (up to the slip setpoint), the brakes are applied to that wheel and the driving torque is transferred through the axle differential to the wheel with the higher traction. This provides superb capabilities when there are diagonal traction losses (ie. left front/right rear).

ADB-X remains active when DSC is deactivated. Furthermore, ADB-X can develop full capability because the engine power is not reduced, even during extreme four wheel drive operation. Only that wheel which has a low traction receives the brake application.

The brake disc can overheat with excessive ADB-X intervention with DSC deactivated. In this situation, the operation is discontinued at a disc temperature of approx. 700 °C and is resumed when this temperature drops below approx. 400 °C. This is a calculation performed by the DSC control unit based on brake application time, pressure, wheel speed, etc.

■ Hill Decent Control (HDC)

As on previous all wheel drive vehicles in the BMW line, the E61 all-wheel drive also features the hill descent control facility for safe vehicle operation on steep downhill inclines. The HDC stabilizes the vehicle and prevents the wheels locking. The DSC8+ module controls the build-up of braking pressure at all four wheels so that the vehicle drives downhill at a speed of approx. 7.5 mph (12 km/h).

The HDC function is activated in the central information display via the menu:

Settings => Vehicle settings => HDC

The HDC ON function can be activated by setting a tick in the menu and deactivated by removing the tick.

Furthermore, the HDC ON/OFF function can be selected with one of the two free buttons (asterisk, hash) in the steering wheel button menu.



Menu HDC ON / Active

■ Dry Braking

The water spray produced in wet conditions coats the brake discs with a water film, causing delayed response of the brakes. In connection with previous systems it was therefore recommended to operate the brakes from time to time.

The dry braking function is dependent on the position of the wiper switch and therefore on the signal of the rain/lights sensor. The brake discs are kept dry by lightly applying the brake pads cyclically as required, this achieving improved braking response in wet conditions.

While doing so, the pressure in the brake system is increased by approx. 1 bar and the brake pads are applied for approx. 1.5 seconds.

Dry braking takes place under following conditions:

- Driving speed > 70 km/h
- Continuous wipe operation in stage 1 or 2

The repeat interval depends on the wiper stage:

- Continuous wipe stage 1 - 200 s
- Continuous wipe stage 2 - 120 s
- Generally 90 s as from 09/2005

This applies only when the driver himself does not apply the brake during this time.

The driver notices no deceleration or noise.



Left disc with water film before dry braking Right brake disc after dry braking

■ Brake Standby

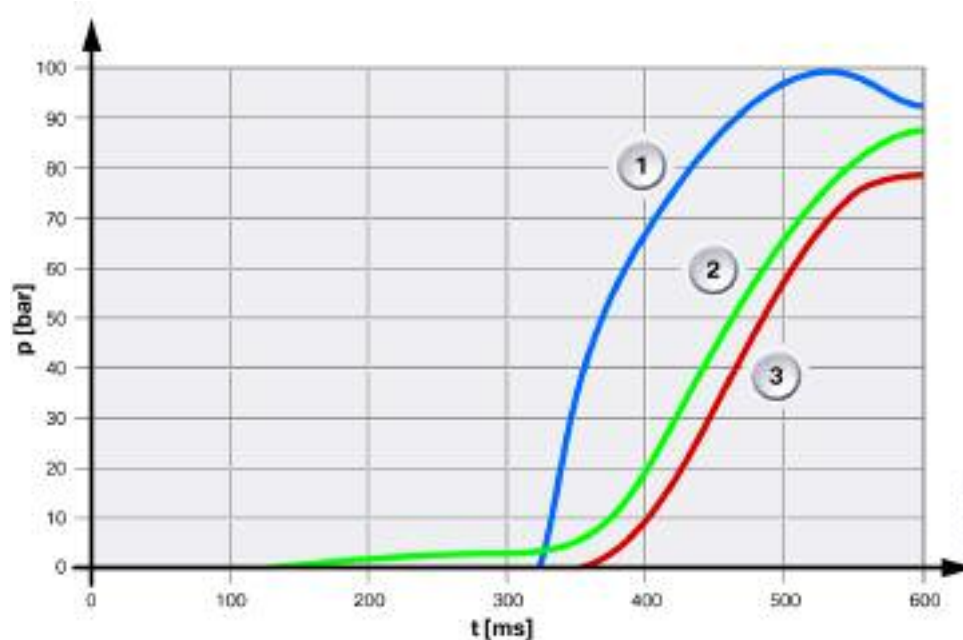
Quick release of the accelerator pedal causes the brake pads to be applied against the brake disc thus reducing the stopping distance (by approx.. 30 cm/100 km/h) during emergency braking. The DSC module builds up slight brake pressure (approx. 2.5 bar) temporarily (approx. 0.5 seconds) in order to eliminate the clearance between the brake pad and brake disc by applying the brake pads.

The brake standby function is activated under following conditions:

- Driving speed > 70 km/h
- Minimum time between brake application 8 s
- The brake standby function is not activated in connection with sudden acceleration (sports driving style).

The DME/DDE control unit makes available the signal indicating quick release of the accelerator pedal via the PT-CAN.

The sensitive driver may perceive a slightly harder brake pedal. No delay or noise is discernible for the driver.



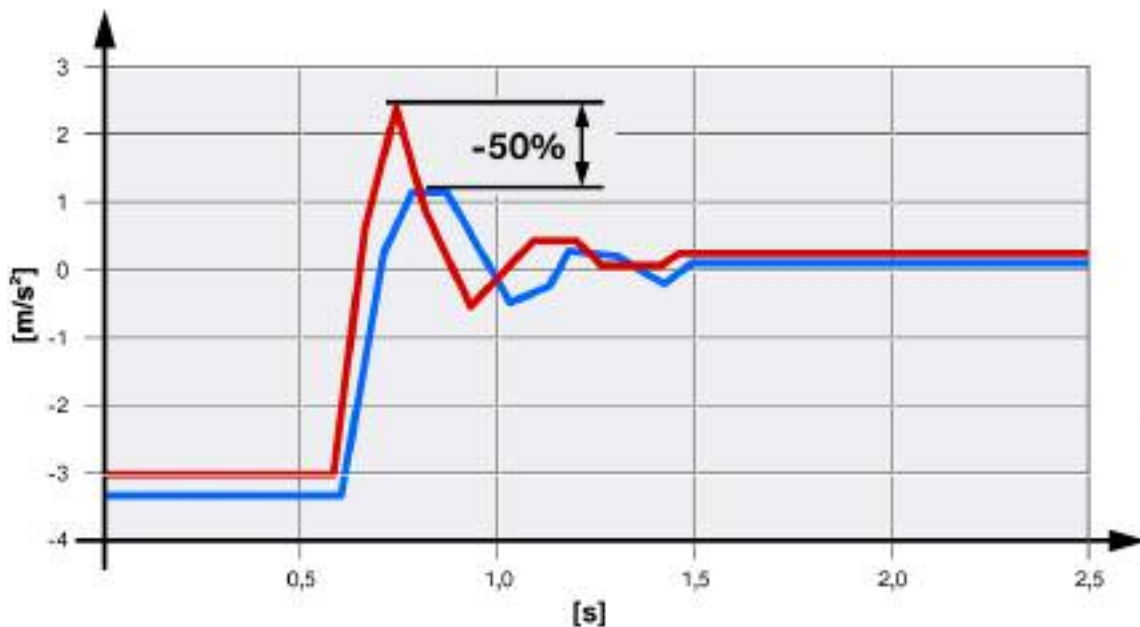
Index	Explanation
P	Braking pressure in Bar
T	Time in milliseconds
1	Pilot pressure applied by driver
2	Braking pressure progression with brake standby
3	Braking pressure progression without brake standby

■ Automatic Soft Stop

Due to the transition from sliding friction to static friction on the brake disc, a stopping jolt occurs when braking to a standstill where the occupants perceive an increased feeling of deceleration.

When braking lightly (< 25 bar) at constant pressure to bring the vehicle to a halt, the soft stop function automatically reduces the braking pressure at the rear axle just before the vehicle comes to a stop. This consequently reduces the positive acceleration peak perceived by the occupants by approx. 50% while extending the action time.

The speed and standstill status are recognized by way of the wheel speed sensors.



Index	Explanation
m/s ²	Deceleration
s	Time in seconds
Red	Deceleration without soft stop
Blue	Deceleration with soft stop
-50%	Reduction of occupant deceleration

Note: This function is inactive at medium to high deceleration or in the event of ABS control in order not to lengthen the stopping distance.

■ Fading Compensation

High temperatures ($> 550^{\circ}\text{C}$) can occur at the brake discs when driving downhill over long periods or as the result of extreme multiple braking operations (> 80 bar). These high temperatures cause a change in the coefficient of friction of the brake pads resulting in the braking effect diminishing (fading).

For this purpose, the temperature of the brake disc is calculated by means of a temperature model contained in the DSC8+ software. The braking pressure applied by the driver is measured by the delivery pressure sensor and compared with the current vehicle deceleration (target/actual value).

When the braking effect diminishes, the fading compensation provides assistance for the driver in that pressure is additionally built up by the DSC module.



Brake Disc with Fading

■ Drive-off Assistant

When negotiating uphill gradients, the drive-off assistant holds the vehicle for a short time (approx. 1.5 s) after releasing the brake so that the vehicle drives off comfortably without the need to use the handbrake. The braking pressure required by the driver to hold the vehicle is maintained automatically in the system.

When driving off, the braking pressure is not reduced before the torque is sufficient for the vehicle to drive off. The holding pressure in the brake system (10 to max. 70 bar) is dependent on the uphill gradient.

Uphill gradients are detected by the DSC sensor with the aid of a longitudinal acceleration sensor.

The function is active both when driving forwards (transmission in Drive) and when reversing (transmission in Reverse) on uphill gradients (up to 50 %).



Drive-off Assistant Function

NOTES

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Service Information

Safety Notice!!!

On a vehicle equipped with an automatic transmission, when driving onto brake analyzers, move the selector lever to the "N" position. On a vehicle equipped with a manual transmission, do not release the clutch pedal once on the brake analyzer.

This keeps the transfer case clutch open and the vehicle cannot be pulled off the analyzer.



Towing: Use only a flatbed carrier for all xDrive vehicles!

Oil, Transfer Case, and Clutch Monitoring

■ Oil

All xDrive transfer cases use Shell Gear oil part number 83 22 0 306 816.

There is no scheduled service for the transfer case oil. Oil Monitoring is performed by the VTG control module to determine when a service (change) is due. The VTG calculates transfer case and clutch wear based on the amount of slip, engagement pressure (torque), speed and mileage.

This calculation accounts for:

- normal "dry" road driving (Integrator 1)
- "adverse" road driving (Integrator 2)
- "other" road extreme driving (Integrator 3)

Depending on individual vehicle use - driving styles and driving conditions, the transfer case oil service interval will vary.

When a service is due, this will be indicated by a Fault Code and additional details are available using the DISplus/ GT1. Service functions provide directions on changing the transfer case oil and updating the VTG control module with the necessary reset and adaption procedure. This is extremely important for CBS.

■ Transfer Case and Clutch

The transfer case and clutch have separate monitoring characteristics. These values are stored as adaptive values in the VGSG control unit and must be transferred to a new control unit if replaced.

The value for both can be obtained using the diagnostic software under:

Control Unit Functions => VTG => Diagnosis requests => Transmission

Control Unit Functions => VTG => Diagnosis requests => Clutch

Diagnosis

Diagnosis is available for fault repairs and service procedures using the DISplus/GT1.

The test plan for the VGSG contains valuable information on:

- Replacing control unit
- Replacing transfer case
- Transferring adaptation values
 - Automatic
 - Manual
- Reading out adaptation values

Programming (flashing)

Both the transfer case control unit (VTG) and the DSC control unit are programmable and the new control unit(s) must be programmed when replaced. The wear values stored in the VTG control module (to be replaced) must be transferred to the replacement VTG.

Warning Indicator Lamps

The warning indicator lamps for the xDrive / DSC are found in the instrument cluster as shown on the bottom of this page.



The warning indicator lamps and acoustic signals (gong) are assigned to the xDrive / DSC system states of malfunction described on the next two pages.

Check Control Messages Relating to xDrive / DXC8+

Fixed indicator lamp	Variable indicator lamp	Check control message	Information in central information display
		DSC disabled!	You have disabled DSC. Restricted vehicle stability while accelerating and cornering.
		DTC enabled, DSC restricted!	DTC enabled. Dynamic traction control DTC increases forward propulsion on unpaved surfaces, however, it decreases vehicle stability.
		DSC failed! Drive with moderation	DBC failed. No additional braking assistance from DBC in emergency braking situations. Drive with moderation. Have checked by your BMW dealer as soon as possible.
		DSC failed! Drive with moderation	DSC failed. Restricted vehicle stability while accelerating and cornering. Drive with moderation. Have checked by your BMW dealer as soon as possible.
		Control systems! Drive with moderation	Brake and vehicle control systems failed. Reduced braking and vehicle stability. Avoid abrupt braking where possible. Have checked by nearest BMW dealer.
		Control systems! Drive with moderation	Brake and vehicle control systems failed. Drive with moderation, avoid abrupt braking where possible. Have checked by nearest BMW dealer.
		Brake pads! Replace	The brake pads are worn. Have replaced by nearest BMW dealer.
		Brake fluid! Stop cautiously	Brake fluid level too low. Reduced braking efficiency. Stop cautiously. Contact nearest BMW dealer.
		Brakes too hot! Allow to cool down	Brakes too hot Critical temperature as a result of permanent heavy load. Danger - reduced braking efficiency. Allow brakes to cool down. Stop if necessary.

Check Control Messages Relating to xDrive / DXC8+ (cont'd)

Fixed indicator lamp	Variable indicator lamp	Check control message	Information in central information display
		Brakes overheated! Allow to cool down	Brakes overheated Critical temperature exceeded. Braking efficiency no longer guaranteed. Stop at the next opportunity and allow to cool down substantially.
		4x4 system and DSC failed!	4x4 system and DSC failed! Vehicle stability restricted. Drive with moderation. Have checked by your BMW dealer as soon as possible.
		4x4 system defective! Drive with moderation	4x4 system defective Vehicle stability restricted. Drive with moderation. Have checked by your BMW dealer as soon as possible.
		4x4 system, DSC and ABS failed!	4x4 system, DSC and ABS failed! Vehicle stability restricted. Drive with moderation. Have checked by your BMW dealer as soon as possible.
		4x4 System, DSC, ABS and emergency EBV failed!	4x4 System, DSC, ABS and emergency EBV failed! Vehicle stability restricted. Drive with moderation. Have checked immediately by your BMW dealer.
		HDC enabled!	
		HDC disabled!	HDC disabled. Hill descent control HDC is disabled at speed above 60 km/h (37 mph). System can be re-enabled at speed below 35 km/h (22 mph).
		No HDC control! Drive slower	HDC not possible! Control range ends at 35 km/h (22 mph). To use HDC, reduce speed accordingly.
		HDC currently not available!	HDC not available. Automatic brake intervention interrupted for safety reasons as brakes are overheated. Shift down and drive carefully in order to reduce temperature.
		Drive-off assistant inactive!	Drive-off assistant inactive Caution, vehicle can roll back! Have checked by your BMW dealer at next opportunity.
		Electronics fault! Stop cautiously	Central vehicle electronics failed. Continued journey not possible. Contact nearest BMW dealer.